

±18V 总线故障保护、3V 至 5.5V、全双工 RS-485 收发器

UM3481F SOP8/SOP14
UM13082F SOP8/SOP14

1 描述

UM3481F 和 UM13082F 均为具备 ±18V 总线故障保护的全双工 RS-422/RS-485 收发器，由 3V 至 5.5V 单电源供电。这些器件提供两种速率等级。UM3481F 支持 1Mbps 传输速率，UM13082F 支持 20Mbps 传输速率。总线接口引脚在所有工作模式下均具备过压保护功能，确保在恶劣的工业环境中实现稳健的通信。

这些器件还集成 IEC ESD 保护功能，无需额外的系统级保护元件。扩展的 ±15V 共模电压范围确保了在较长的电缆长度下和/或存在较大接地环路电压时，数据通信仍能保持可靠。增强型 250mV 接收器迟滞特性可实现出色的抗噪声能力。此外，接收器内置的故障安全功能可确保在输入开路或短路时维持逻辑高电平。

UM3481F 和 UM13082F 均采用 SOP8 和 SOP14 封装，所有设备均专为空间受限的应用而设计，工作环境温度范围扩展至 -40°C 至 125°C。

2 特性

- 符合或超出 TIA/EIA-485A 和 TIA/EIA-422B 标准的要求
- 3V 至 5.5V 电源电压
- 总线 I/O 保护
 - ±18V 直流总线故障保护
 - ±8kV 人体放电模型
- 扩展的运行共模电压范围：±15V
- 闩锁 (Latch-up) 性能超过 200mA，符合 JESD 78 规范
- 适用热插拔功能的无干扰上电/断电
- 差分输出超过 2.1V，在 5V 电源下与 PROFIBUS 兼容
- 数据传输速率：
 - 1Mbps (UM3481F)
 - 20Mbps (UM13082F)
- 工作环境温度范围：-40°C 至 125°C
- 增强型接收器迟滞，增强抗噪能力
- 开路、短路和空闲总线失效防护
- 热关断
- 1/8 单位负载 (多达 256 个总线节点)

3 应用

- 汽车数据链路
- 工业控制局域网
- 综合业务数字网
- 楼宇自动化
- 电表
- 适用于电磁干扰敏感应用的收发器

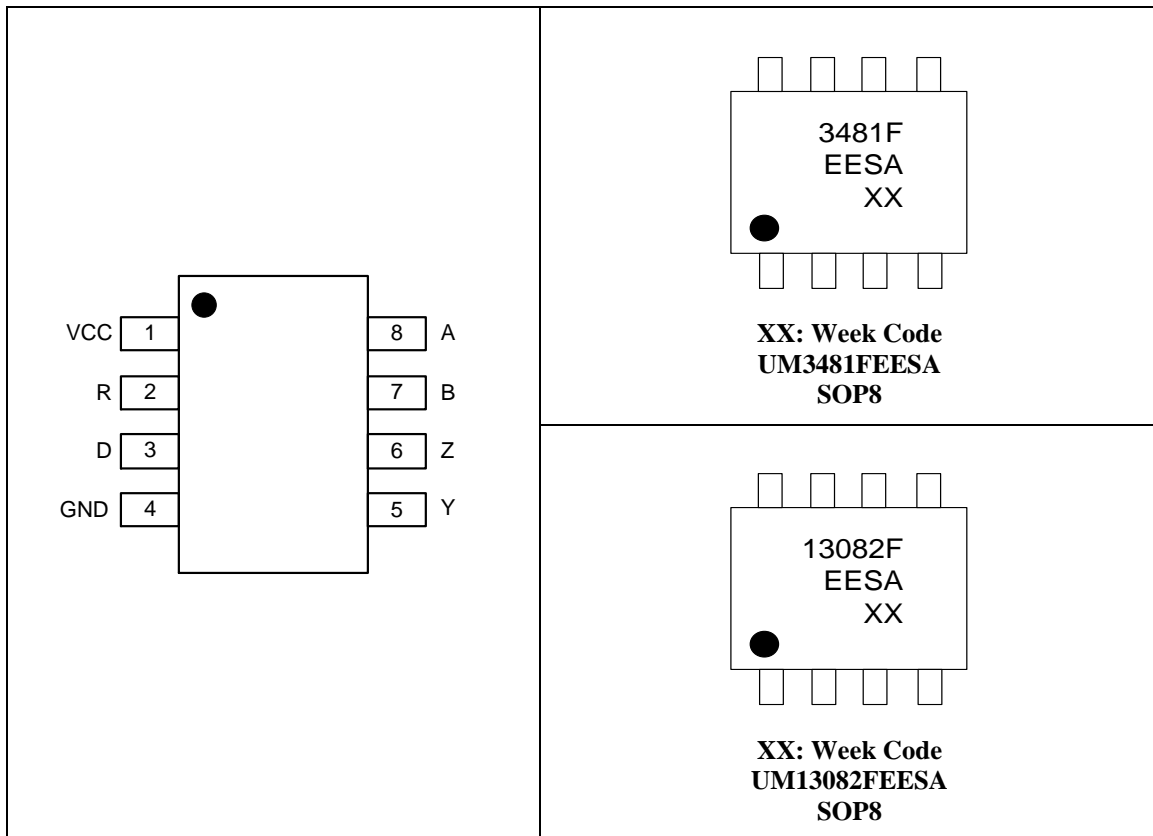
4 Selection Guide

| Part Number | Bus fault Voltage (V) | Data Rate (Mbps) |
|-------------|-----------------------|------------------|
| UM3481F | ±18 | 1 |
| UM13082F | ±18 | 20 |

5 Ordering Information

| Part Number | Mark Code | Package Type | Shipping Qty |
|--------------|------------|--------------|----------------------------|
| UM3481FEESA | 3481FEESA | SOP8 | 3000pcs/13Inch Tape & Reel |
| UM3481FEESE | UM3481F | SOP14 | 2500pcs/13Inch Tape & Reel |
| UM13082FEESA | 13082FEESA | SOP8 | 3000pcs/13Inch Tape & Reel |
| UM13082FEESE | UM13082F | SOP14 | 2500pcs/13Inch Tape & Reel |

6 Pin Configuration and Function



6 Pin Configuration and Function (continued)

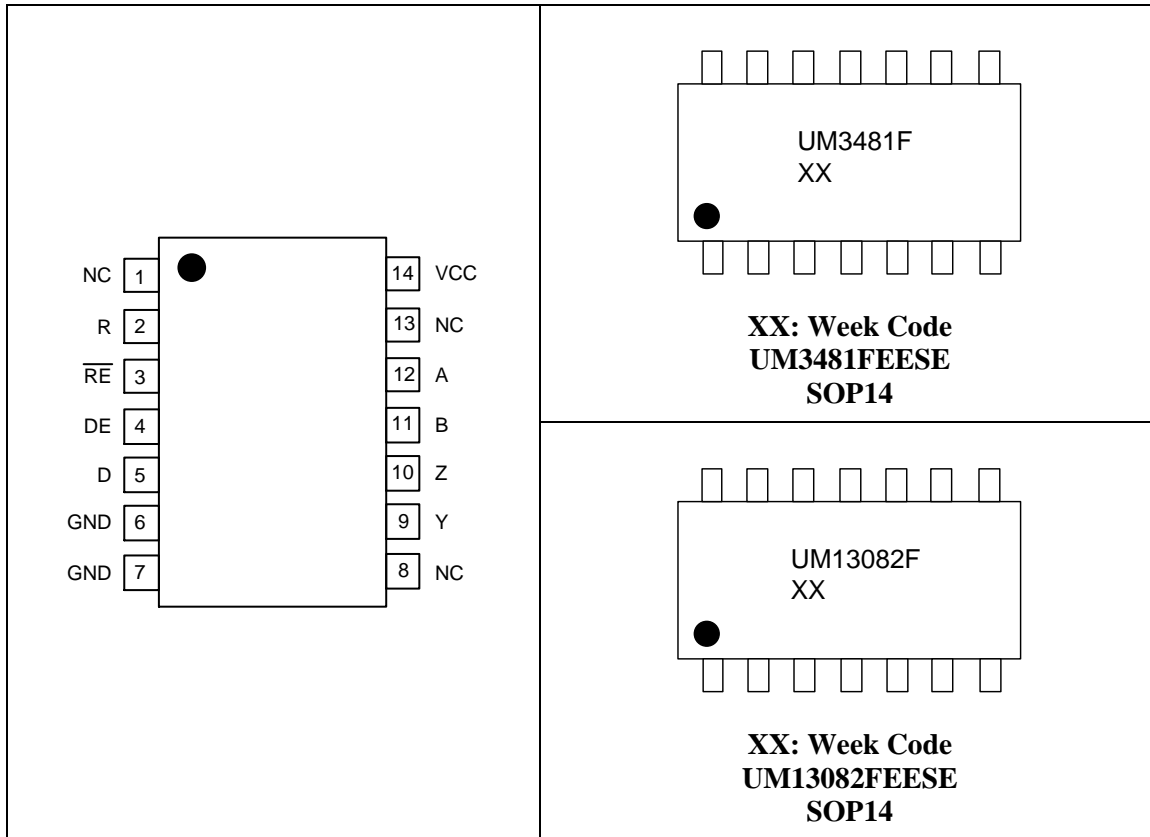


Table 6-1. Pin Functions

| Pin Name | Function |
|-----------------|-------------------------------|
| R | Receiver data output. |
| \overline{RE} | Receiver enable, active low. |
| DE | Driver enable, active high. |
| D | Driver data input. |
| NC | Not connected internally. |
| GND | Ground. |
| Y | Driver non-inverting output. |
| Z | Driver inverting output. |
| B | Receiver inverting input. |
| A | Receiver non-inverting input. |
| VCC | 3 V to 5.5 V bus supply. |

7 Specifications

7.1 Absolute Maximum Ratings (Note 1)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------|----------------------------------------------------|------------|------|-----|-----|------|
| V _{CC} | Supply voltage | | -0.5 | | 6.5 | V |
| V _I | Voltage on A, B, Y, Z | | -18 | | 18 | V |
| | Voltage on any logic pin (D, DE, RE) | | -0.3 | | 6.5 | V |
| V _{ESD} | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 | Bus pins | | ±8 | | kV |
| | | Other pins | | ±2 | | kV |
| I _O | RXD output current | | -24 | | 24 | mA |
| T _{STG} | Storage temperature | | -65 | | 150 | °C |
| T _L | Lead Temperature for Soldering 10 Seconds | | | | 260 | °C |

Note 1: Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute maximum ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If briefly operating outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not sustain damage, but it may not be fully functional. Operating the device in this manner may affect device reliability, functionality, performance, and shorten the device lifetime.

7.2 Recommended Operating Conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------|---------------------------------------------------------------|------------|-----|-----|-----|------|
| V _{CC} | Supply Voltage | | 3 | | 5.5 | V |
| V _I | Input voltage at any bus terminal (separately or common mode) | Note 1 | -15 | | 15 | V |
| V _{ID} | Differential input voltage | | -15 | | 15 | V |
| I _O | Output current, driver | | -60 | | 60 | mA |
| I _{OR} | Output current, receiver | | -8 | | 8 | mA |
| R _L | Differential load resistance | | 54 | 60 | | Ω |
| 1/ t _{UI} | Signaling rate | UM3481F | | | 1 | Mbps |
| | | UM13082F | | | 20 | Mbps |
| T _A | Operating free-air temperature | | -40 | | 125 | °C |
| T _J | Junction temperature | | -40 | | 150 | °C |

Note 1: The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

7.3 Electrical Characteristics (Static) (Note 1)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^\circ\text{C}$ and supply voltage of $V_{CC} = 5\text{ V}$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|------------------------------------------------------------|--------------------------------------------------------------------------------------------------|------|------|-----|---------------|
| Supply | | | | | | |
| $V_{UVD(VCC)RISING}$ | Rising under-voltage threshold on VCC | | | 2.6 | 2.8 | V |
| $V_{UVD(VCC)FALLING}$ | Falling under-voltage threshold on VCC | | 1.95 | 2.35 | | V |
| $V_{UVD(VCC)HYS}$ | Hysteresis on under-voltage of VCC | | | 250 | | mV |
| I_{CC} | Supply current, $V_{CC} = 4.5\text{ V to }5.5\text{ V}$ | $\overline{RE} = 0\text{ V}, DE = V_{CC}$, No load (Driver and receiver enabled) | | 1.9 | 3 | mA |
| | | $\overline{RE} = V_{CC}, DE = V_{CC}$, No load (Driver enabled, receiver disabled) | | 1.9 | 3 | mA |
| | | $\overline{RE} = 0\text{ V}, DE = 0\text{ V}$, No load (Driver disabled, receiver enabled) | | 1.2 | 2.4 | mA |
| | | $\overline{RE} = V_{CC}, DE = 0\text{ V}$, D = open, No load (Driver and receiver disabled) | | 4.3 | 10 | μA |
| I_{CC} | Supply current, $V_{CC} = 3\text{ V to }3.6\text{ V}$ | $\overline{RE} = 0\text{ V}, DE = V_{CC}$, No load (Driver and receiver enabled) | | 1.8 | 2.7 | mA |
| | | $\overline{RE} = V_{CC}, DE = V_{CC}$, No load (Driver enabled, receiver disabled) | | 1.8 | 2.7 | mA |
| | | $\overline{RE} = 0\text{ V}, DE = 0\text{ V}$, No load (Driver disabled, receiver enabled) | | 1.1 | 2.2 | mA |
| | | $\overline{RE} = V_{CC}, DE = 0\text{ V}$, D = open, No load (Driver and receiver disabled) | | 3.2 | 8 | μA |

7.3 Electrical Characteristics (Static) (Note 1) (continued)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^\circ\text{C}$ and supply voltage of $V_{CC} = 5\text{ V}$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-----------------------------------------------------------|------------------------------------------------------------------------------------------------------------------|----------------------|----------------------|-----|------|
| Driver | | | | | | |
| V _{OD} | Driver differential output voltage magnitude | R _L = 60 Ω, -15 V ≤ V _{TEST} ≤ 15 V, See Figure 8-1 | 1.5 | 3.3 | | V |
| | | R _L = 60 Ω, -15 V ≤ V _{TEST} ≤ 15V, 4.5 V ≤ V _{CC} ≤ 5.5 V, See Figure 8-1 | 2.1 | 3.3 | | V |
| | | R _L = 100 Ω, See Figure 8-2 | 2 | 4 | | V |
| | | R _L = 54 Ω, See Figure 8-2 | 1.5 | 3.3 | | V |
| Δ V _{OD} | Change in magnitude of driver differential output voltage | R _L = 54 Ω or 100 Ω See Figure 8-2 | -50 | | 50 | mV |
| V _{OC} | Common-mode output voltage | R _L = 54 Ω or 100 Ω See Figure 8-2 | 1 | V _{CC} /2 | 3 | V |
| V _{OC(SS)} | Steady-state common-mode output voltage | R _L = 54 Ω or 100 Ω See Figure 8-2 | -50 | | 50 | mV |
| I _{OS} | Short-circuit output current | DE = V _{CC} , -18V ≤ (V _Y or V _Z) ≤ 18V | -250 | | 250 | mA |
| Receiver | | | | | | |
| I _I | Bus input current | DE = 0V, V _{CC} = 0V or 5.5V, V _I = 12V | | | 125 | μA |
| | | DE = 0V, V _{CC} = 0V or 5.5V, V _I = -7V | -100 | | | |
| V _{TH+} | Positive-going input threshold voltage | Over common-mode range of ± 15 V | | 125 | 200 | mV |
| V _{TH-} | Negative-going input threshold voltage | | -200 | -125 | | |
| V _{HYS} | Input hysteresis | | | | 250 | |
| C _{A,B} | Input differential capacitance | Measured between A and B, f = 1 MHz | | 50 | | pF |
| V _{OH} | Output high voltage | I _{OH} = -8 mA | V _{CC} -0.4 | V _{CC} -0.2 | | V |
| V _{OL} | Output low voltage | I _{OL} = 8 mA | | 0.2 | 0.4 | V |
| I _{OZ} | Output high-impedance current | V _O = 0 V or V _{CC} , R _E = V _{CC} | -1 | | 1 | μA |

7.3 Electrical Characteristics (Static) (Note 1) (continued)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^{\circ}\text{C}$ and supply voltage of $V_{CC} = 5\text{ V}$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------------|----------------------------------------------|--------------------------------------|-----|-----|-----|--------------------|
| Logic | | | | | | |
| V_{IH} | Input High Voltage on DE, D, \overline{RE} | $V_{CC} = 4.5$ to 5.5 V | 2.8 | | | V |
| | | $V_{CC} = 3.0$ to 3.6 V | 2.1 | | | V |
| V_{IL} | Input low Voltage on DE, D, \overline{RE} | $V_{CC} = 4.5$ to 5.5 V | | | 0.8 | V |
| | | $V_{CC} = 3.0$ to 3.6 V | | | 0.8 | V |
| I_I | Input current on DE pin | $0\text{ V} \leq V_{IN} \leq V_{CC}$ | | 10 | 25 | μA |
| | Input current on D, \overline{RE} pin | $0\text{ V} \leq V_{IN} \leq V_{CC}$ | -10 | | | μA |
| Thermal Protection | | | | | | |
| T_{SD} | Thermal shutdown threshold | Temperature rising | | 150 | | $^{\circ}\text{C}$ |
| T_{HYS} | Thermal shutdown hysteresis | | | 10 | | $^{\circ}\text{C}$ |

7.4 Electrical Characteristics (Dynamic)—1Mbps (Note 1)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^\circ\text{C}$ and supply voltage of $V_{CC}=5V$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--------------------|-----------------------------------------------------------------|-------------------------------------------------------------------|-----------------------------------------------------------------|-----|------|---------------|----|
| Driver | | | | | | | |
| t_R, t_F | Driver differential output rise/fall time | $R_L = 54\ \Omega$, $C_L = 50\ \text{pF}$, see Figure 8-3 | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | 105 | 128 | 300 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | 130 | 180 | 300 | ns |
| t_{PHL}, t_{PLH} | Driver propagation delay time | | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | | 125 | 240 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | | 141 | 280 | ns |
| $t_{SK(P)}$ | Driver differential output pulse skew, $ t_{PHL} - t_{PLH} $ | | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | | 3 | 20 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | | 2 | 15 | ns |
| t_{PHZ}, t_{PLZ} | Disable time | See Figure 8-4 and Figure 8-5 | | | 200 | ns | |
| t_{PZH}, t_{PZL} | Enable time | $\overline{RE} = 0\ \text{V}$, See Figure 8-4 and Figure 8-5 | | | 300 | ns | |
| t_{PSH}, t_{PSL} | | $\overline{RE} = V_{CC}$, See Figure 8-4 and Figure 8-5 | | 2.6 | 4.6 | μs | |
| t_{PHS}, t_{PLS} | Time to shutdown | $\overline{RE} = V_{CC}$, See Figure 8-4 and Figure 8-5 | 50 | | 500 | ns | |
| Receiver | | | | | | | |
| t_R, t_F | Receiver output rise/fall time | $C_L = 15\ \text{pF}$, see Figure 8-6 | | 8.5 | 15 | ns | |
| t_{PHL}, t_{PLH} | Receiver propagation delay time | | | 55 | 85 | ns | |
| $t_{SK(P)}$ | Receiver output pulse skew, $ t_{PHL} - t_{PLH} $ | | | 1 | 12.5 | ns | |

7.4 Electrical Characteristics (Dynamic)—1Mbps (continued) (Note 1)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^{\circ}\text{C}$ and supply voltage of $V_{CC}=5V$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|-----------------------|------------------------------------|-----|-----|-----|---------------|
| Receiver | | | | | | |
| t_{PHZ} , t_{PLZ} | Receiver disable time | | | 33 | 50 | ns |
| t_{PZL} , t_{PZH} | Receiver enable time | $DE = V_{CC}$, see Figure 8-7 | | 38 | 90 | ns |
| t_{PSL} , t_{PSH} | | $DE = 0\text{ V}$, see Figure 8-8 | | 3 | 4.5 | μs |
| t_{PHS} , t_{PLS} | Time to shutdown | $DE = 0\text{ V}$, see Figure 8-8 | 50 | | 500 | ns |

7.4 Electrical Characteristics (Dynamic)—20Mbps (Note 1)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^\circ\text{C}$ and supply voltage of $V_{CC}=5V$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit | |
|--------------------|-----------------------------------------------------------------|-------------------------------------------------------------------|-----------------------------------------------------------------|-----|-----|---------------|----|
| Driver | | | | | | | |
| t_R, t_F | Driver differential output rise/fall time | $R_L = 54\ \Omega$, $C_L = 50\ \text{pF}$, see Figure 8-3 | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | 3 | 4.4 | 15 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | 3 | 4 | 15 | ns |
| t_{PHL}, t_{PLH} | Driver propagation delay time | | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | 4 | 9 | 30 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | 4 | 7 | 25 | ns |
| $t_{SK(P)}$ | Driver differential output pulse skew, $ t_{PHL} - t_{PLH} $ | | $V_{CC} = 3$ to $3.6\ \text{V}$, Typical at $3.3\ \text{V}$ | | 1 | 3 | ns |
| | | | $V_{CC} = 4.5$ to $5.5\ \text{V}$, Typical at $5\ \text{V}$ | | 1 | 3 | ns |
| t_{PHZ}, t_{PLZ} | Disable time | See Figure 8-4 and Figure 8-5 | | | 200 | ns | |
| t_{PZH}, t_{PZL} | Enable time | $\overline{RE} = 0\ \text{V}$, See Figure 8-4 and Figure 8-5 | | | 50 | ns | |
| t_{PSH}, t_{PSL} | | $\overline{RE} = V_{CC}$, See Figure 8-4 and Figure 8-5 | | 2.5 | 4.5 | μs | |
| t_{PHS}, t_{PLS} | Time to shutdown | $\overline{RE} = V_{CC}$, See Figure 8-4 and Figure 8-5 | 50 | | 500 | ns | |
| Receiver | | | | | | | |
| t_R, t_F | Receiver output rise/fall time | $C_L = 15\ \text{pF}$, see Figure 8-6 | | 4.5 | 7 | ns | |
| t_{PHL}, t_{PLH} | Receiver propagation delay time | | 9 | 12 | 40 | ns | |
| $t_{SK(P)}$ | Receiver output pulse skew, $ t_{PHL} - t_{PLH} $ | | | 0.5 | 5 | ns | |

7.4 Electrical Characteristics (Dynamic)—20Mbps (continued) (Note 1)

$V_{CC} = +3V$ to $+5.5V$, $T_A = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$, unless otherwise noted. All typical values are at $25\text{ }^{\circ}\text{C}$ and supply voltage of $V_{CC}=5V$.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|-----------------------|------------------------------------|-----|-----|-----|---------------|
| Receiver | | | | | | |
| t_{PHZ} , t_{PLZ} | Receiver disable time | | | 13 | 30 | ns |
| t_{PZL} , t_{PZH} | Receiver enable time | $DE = V_{CC}$, see Figure 8-7 | | 17 | 50 | ns |
| t_{PSL} , t_{PSH} | | $DE = 0\text{ V}$, see Figure 8-8 | | 2.9 | 5 | μs |
| t_{PHS} , t_{PLS} | Time to shutdown | $DE = 0\text{ V}$, see Figure 8-8 | 50 | | 500 | ns |

8 Parameter Measurement Information

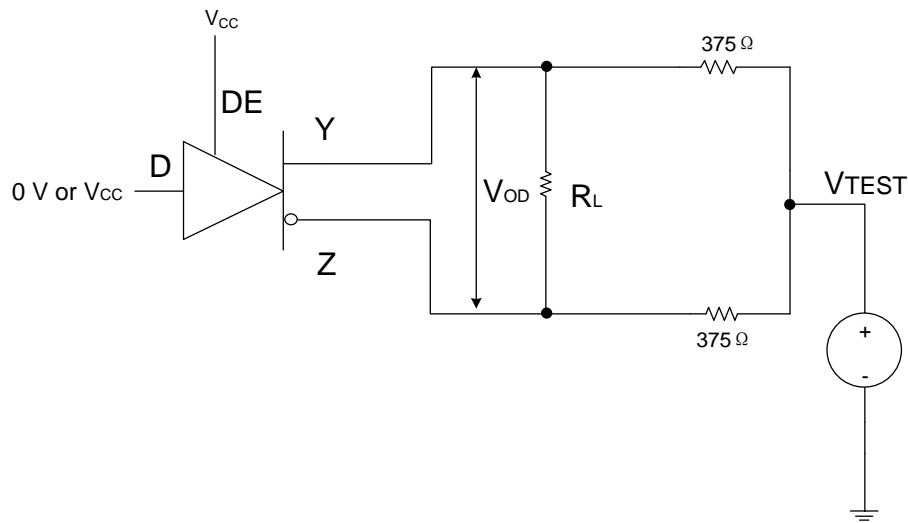


Figure 8-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

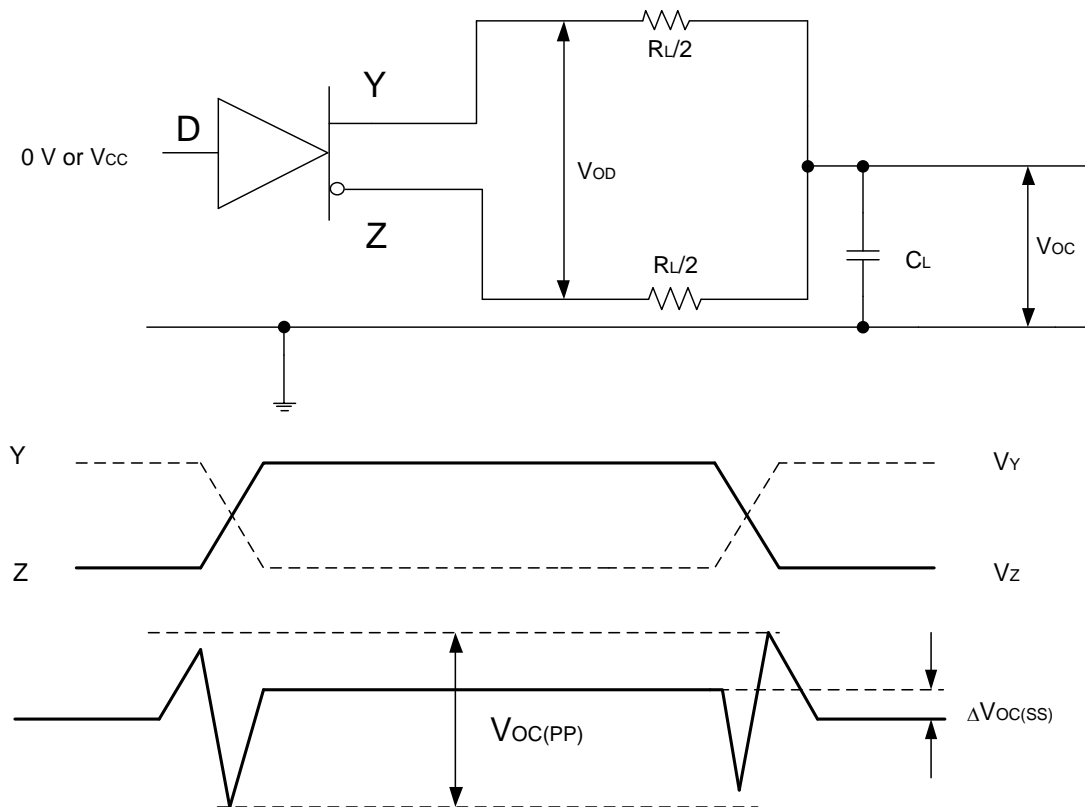


Figure 8-2. Measurement of Driver Differential and Common-Mode Output With RS-485/RS-422 Load

8 Parameter Measurement Information (continued)

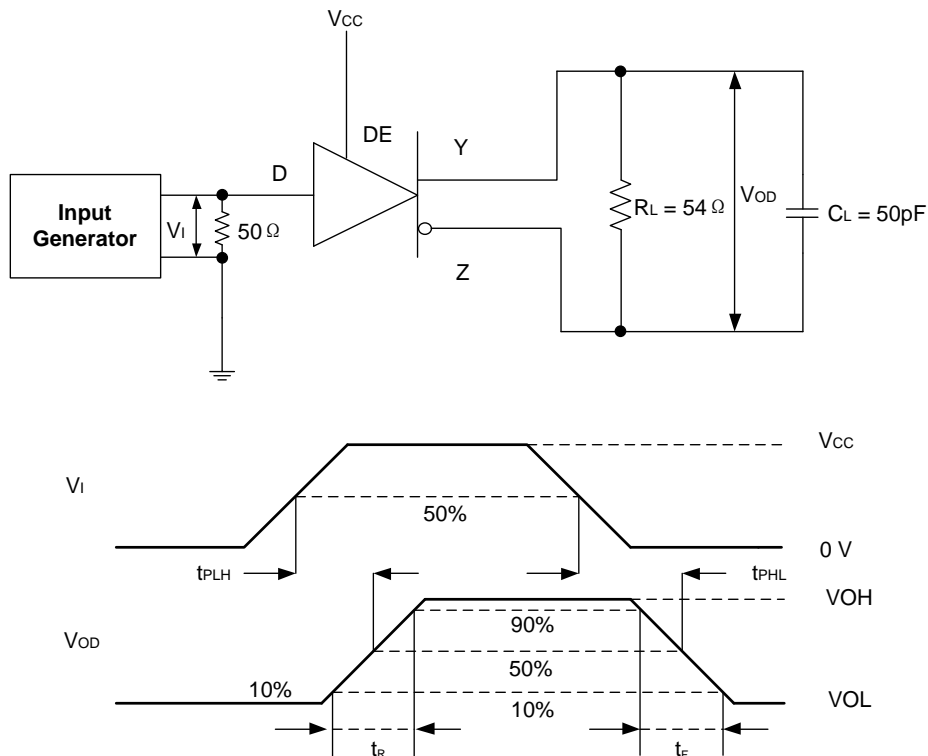


Figure 8-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays

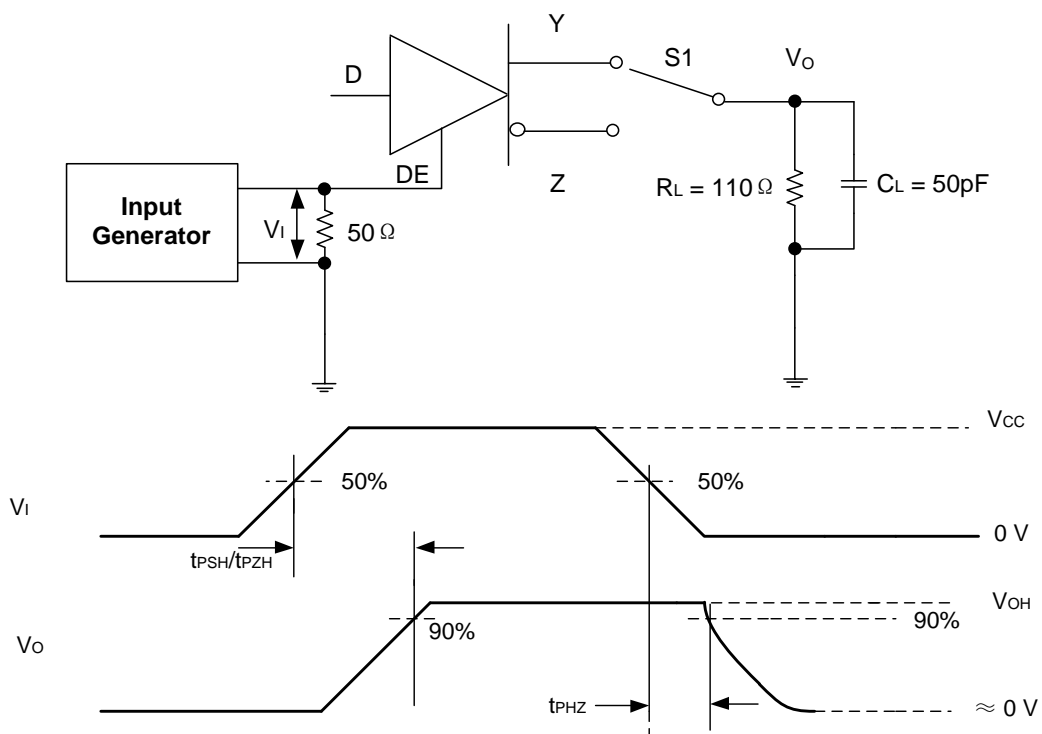


Figure 8-4. Measurement of Driver Enable and Disable Times With Active High Output and Pull-Down Load

8 Parameter Measurement Information (continued)

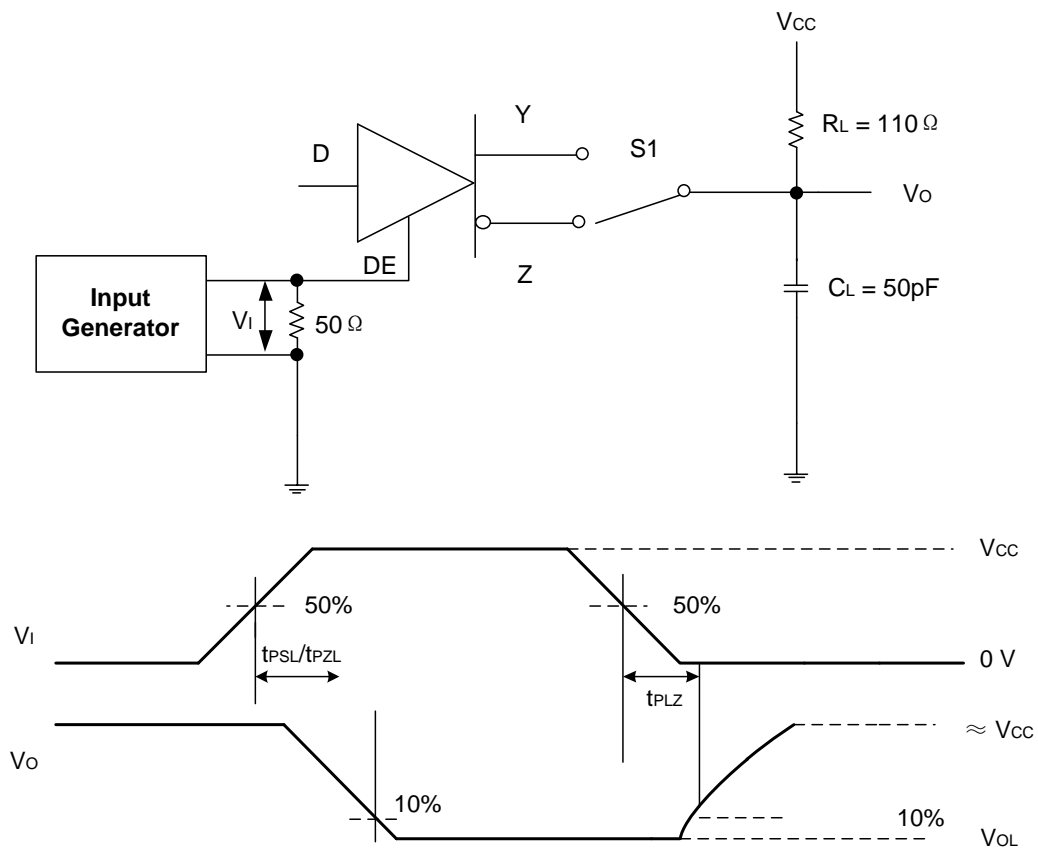


Figure 8-5. Measurement of Driver Enable and Disable Times With Active Low Output and Pull-up Load

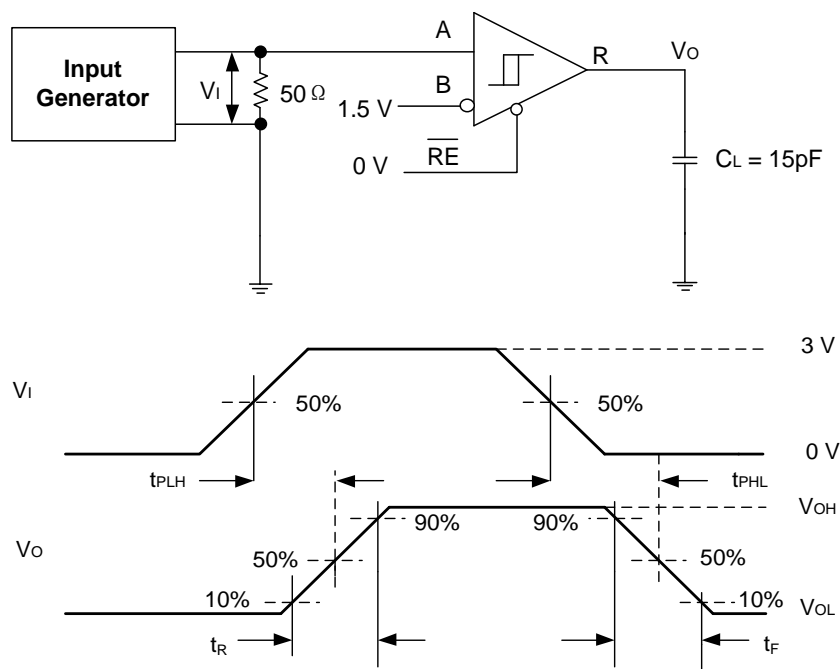


Figure 8-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

8 Parameter Measurement Information (continued)

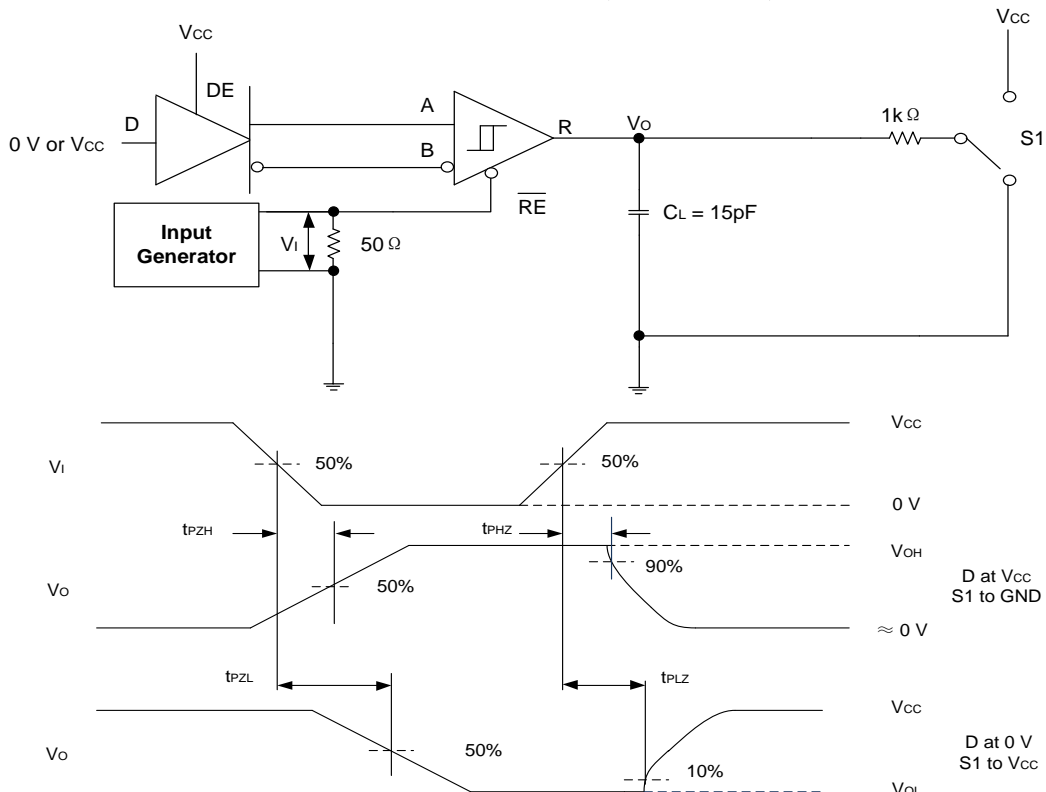


Figure 8-7. Measurement of Receiver Enable/Disable Times With Driver Enabled

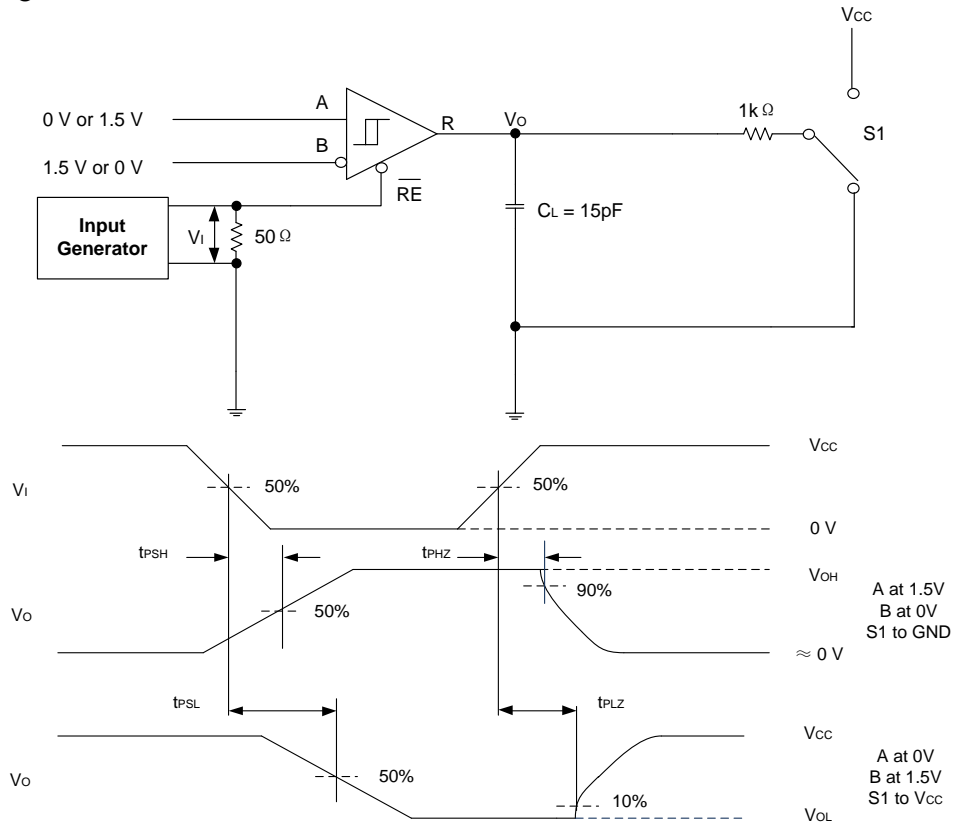


Figure 8-8. Measurement of Receiver Enable Times With Driver Disabled

9 Detailed Description

9.1 Overview

The UM3481F is fault-protected, full duplex RS-485 transceivers available in speed grade suitable for data transmission up to 1Mbps. The UM13082F is fault-protected, full duplex RS-485 transceivers available in speed grade suitable for data transmission up to 20 Mbps. This is beneficial as customers can qualify one device and use it in two different end-applications.

9.2 Functional Block Diagram

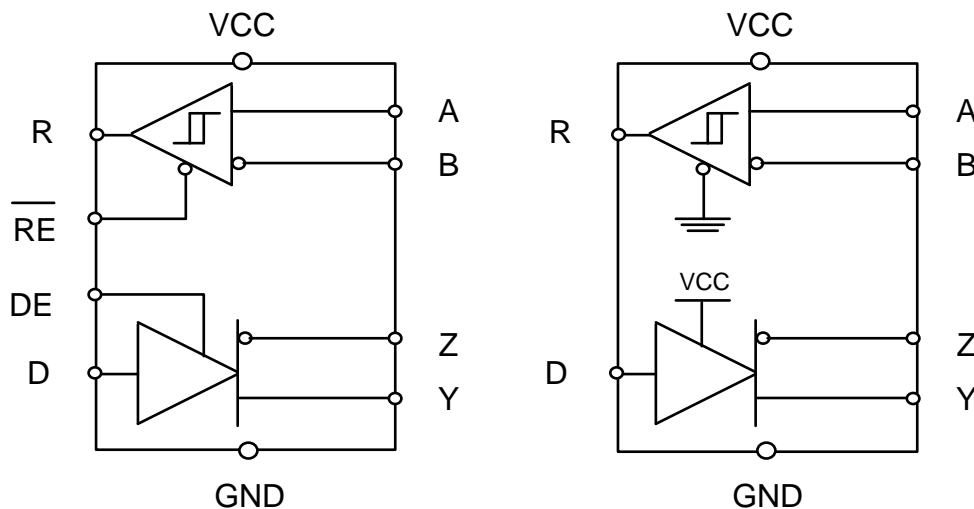


Figure 9-1. Block Diagram

10 Feature Description

10.1 Receiver Fail-Safe Operation

The receivers are fail-safe to invalid bus states caused by the following:

- Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

10.2 Low-Power Shutdown Mode (SOP14 versions)

Driving DE low and \overline{RE} high for longer than 500 ns puts the devices into the shutdown mode. If either DE goes high or \overline{RE} goes low, the counters reset. All devices do not enter the shutdown mode if the enable pins are in disable state for less than 50 ns. This feature prevents the devices from accidentally going into shutdown mode due to skew between DE and \overline{RE} .

10.3 Device Functional Modes

When the driver enable pin, DE, is logic high, the differential outputs Y and Z follow the logic states at data input D. A logic high at D causes Y to turn high and Z to turn low. In this case, the differential output voltage defined as $V_{OD} = V_Y - V_Z$ is positive. When D is low, the output states reverse: Z turns high, Y becomes low, and V_{OD} is negative.

When DE is low, both outputs turn high-impedance. In this condition, the logic state at D is irrelevant. The DE pin has an internal pull-down resistor to ground, thus when left open the driver is disabled (high-impedance) by default. The D pin has an internal pull-up resistor to V_{CC} , thus, when left open while the driver is enabled, output A turns high and B turns low.

Table 10-1. Driver Function Table

| Enable | Input | Output | | Function |
|--------|-------|--------|---|------------------------------------|
| | | Y | Z | |
| DE | D | | | |
| L | X | Z | Z | Driver disabled |
| Open | X | Z | Z | Driver disabled by default |
| H | H | H | L | Actively drive bus high |
| H | L | L | H | Actively drive bus low |
| H | Open | H | L | Actively drive bus high by default |

When the receiver enable pin, \overline{RE} , is logic low, the receiver is enabled. When the differential input voltage defined as $V_{ID} = V_A - V_B$ is higher than the positive input threshold, V_{TH+} , the receiver output, R, turns high. When V_{ID} is lower than the negative input threshold, V_{TH-} , the receiver output, R, turns low. If V_{ID} is between V_{TH+} and V_{TH-} , the output is indeterminate.

When \overline{RE} is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of V_{ID} are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), or the bus lines are shorted to one another (short-circuit), or the bus is not actively driven (idle bus).

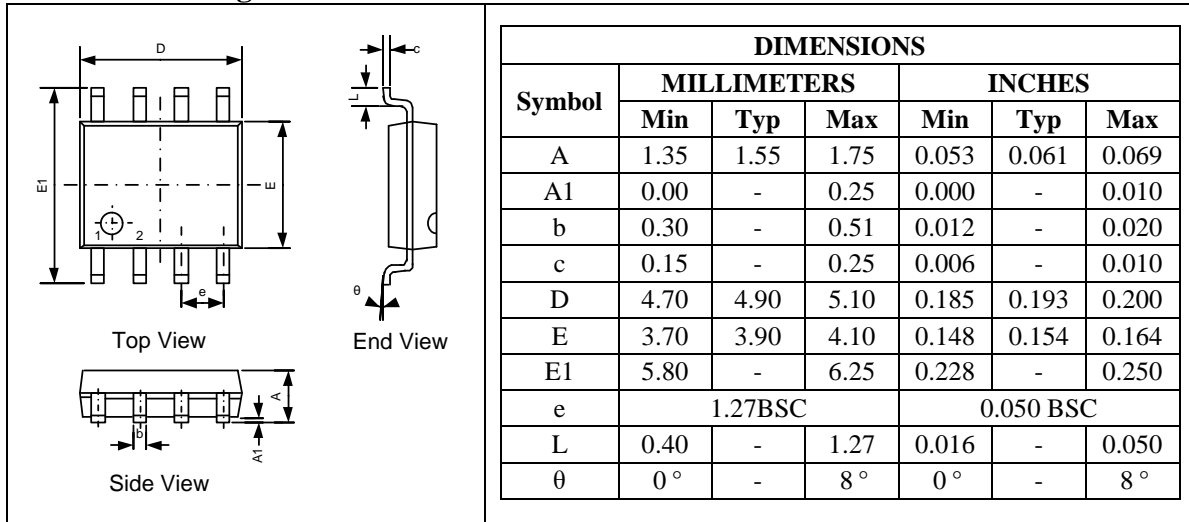
Table 10-2. Receiver Function Table

| Enable | Differential Input | Output | Function |
|--------|------------------------------|--------|------------------------------|
| | | | |
| H | X | Z | Receiver disabled |
| Open | X | Z | Receiver disabled by default |
| L | $V_{TH+} < V_{ID}$ | H | Receive valid bus high |
| L | $V_{TH-} < V_{ID} < V_{TH+}$ | N/A | Indeterminate bus state |
| L | $V_{ID} < V_{TH-}$ | L | Receive valid bus low |
| L | Open-circuit bus | H | Fail-safe high output |
| L | Short-circuit bus | H | Fail-safe high output |
| L | Idle (terminated) bus | H | Fail-safe high output |

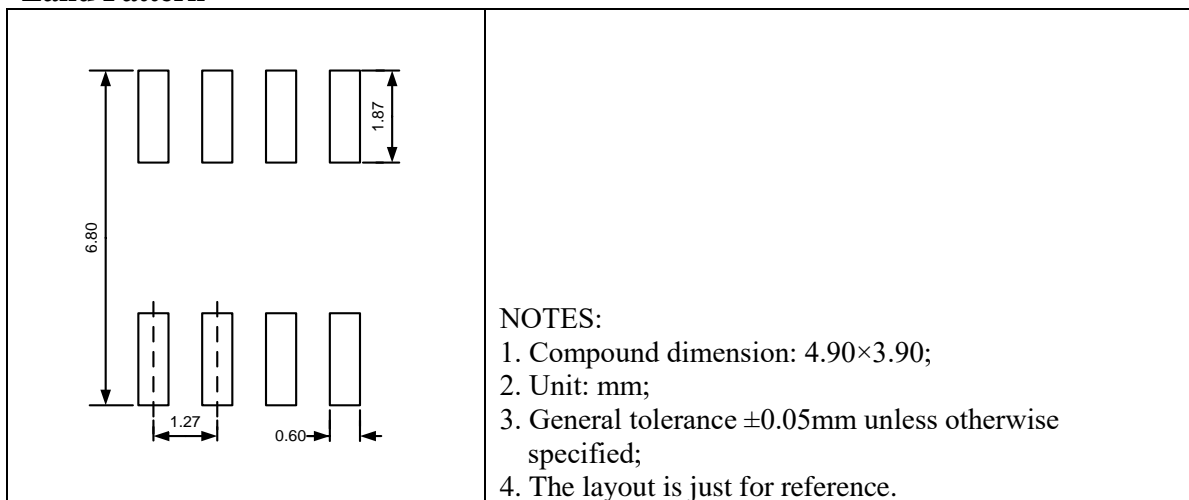
Package Information

SOP8

Outline Drawing

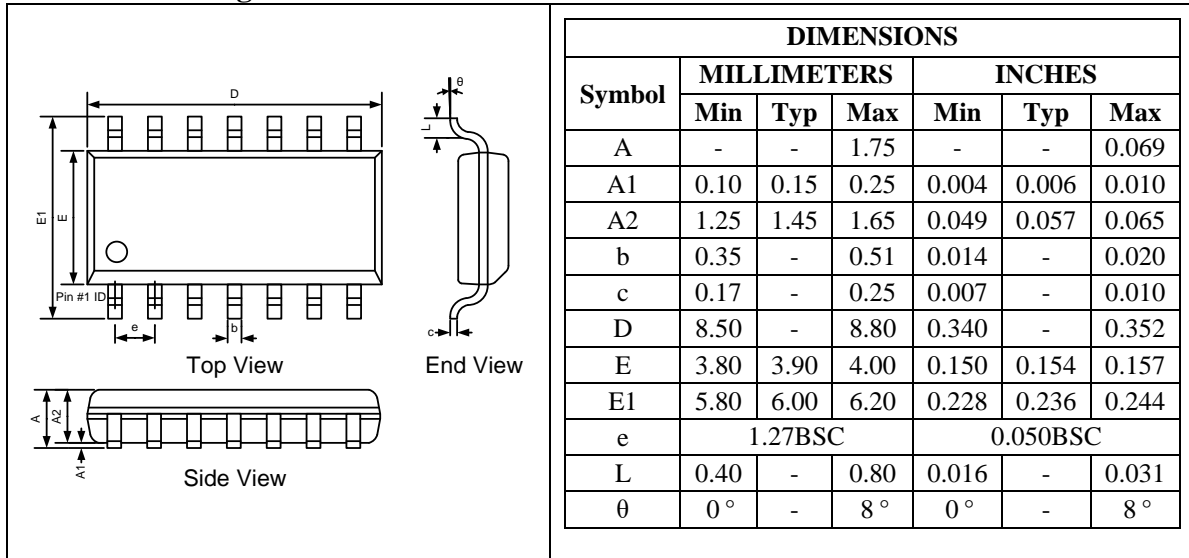


Land Pattern

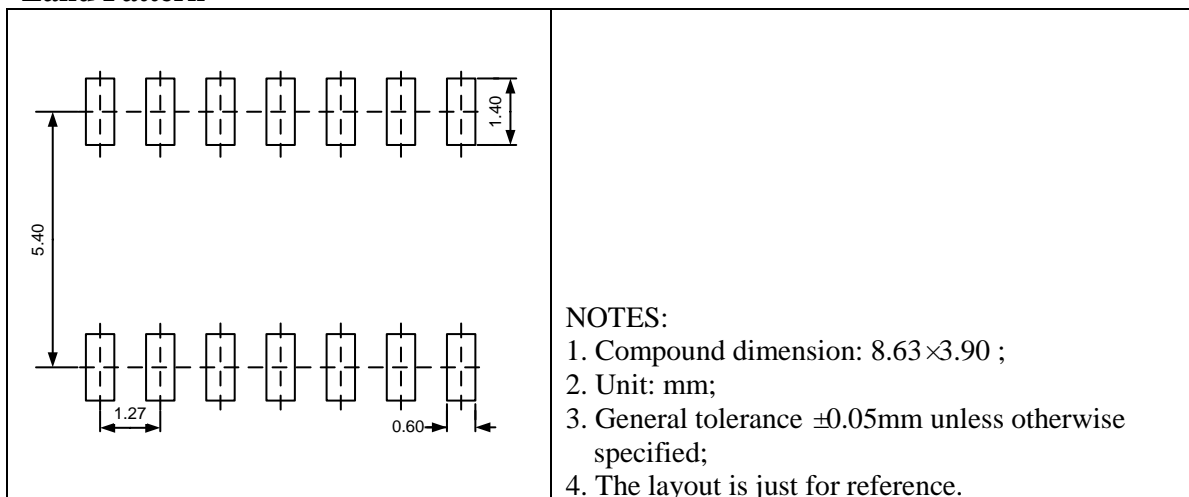


SOP14

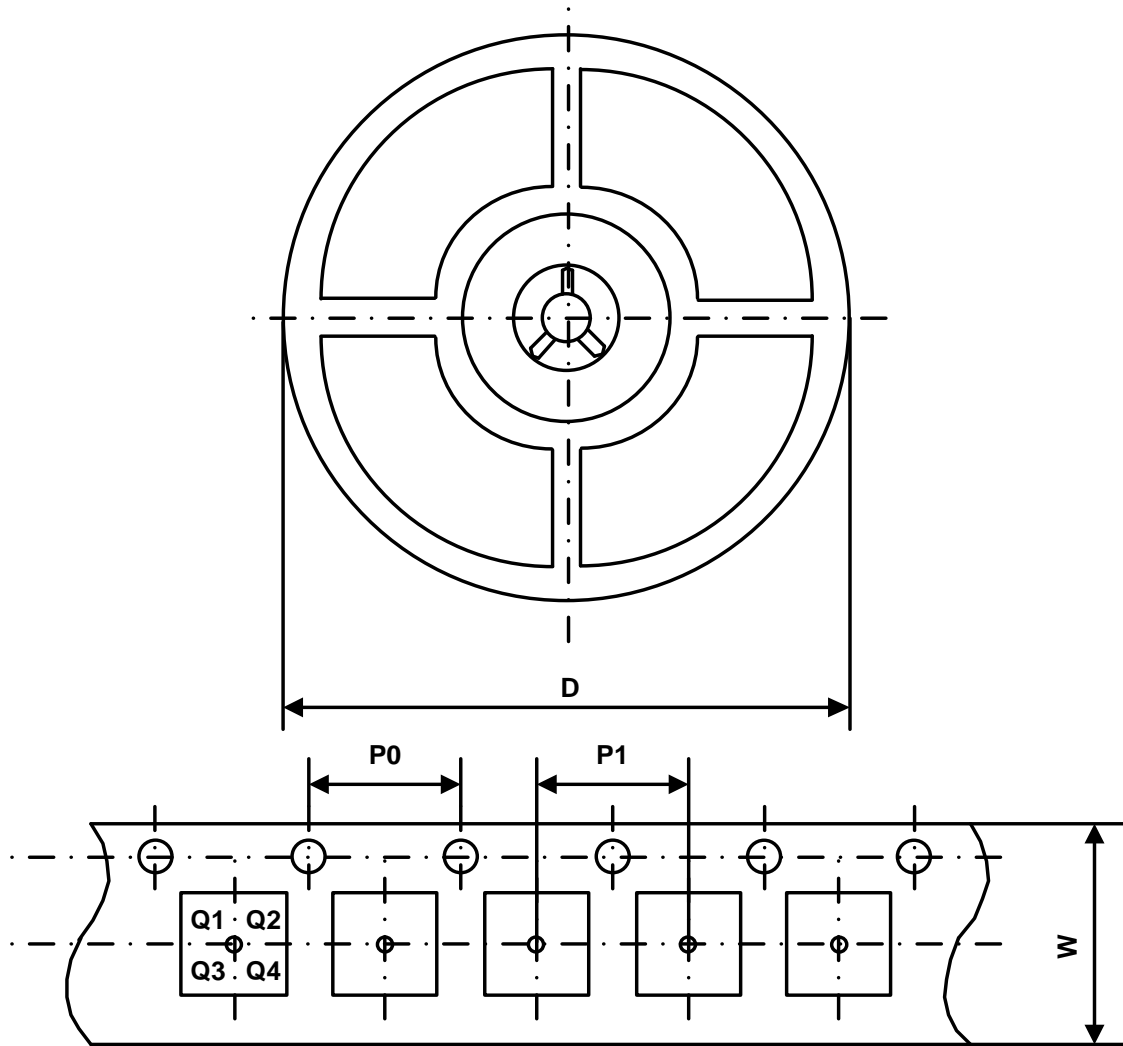
Outline Drawing



Land Pattern



Packing Information



| Part Number | Package Type | Carrier Width (W) | Pitch (P0) | Pitch (P1) | Reel Size (D) | PIN 1 Quadrant |
|---------------|--------------|-------------------|------------|------------|---------------|----------------|
| UM3481FEESA | SOP8 | 12 mm | 4 mm | 8 mm | 330 mm | Q1 |
| UM3481FEESE | SOP14 | 16 mm | 4 mm | 8 mm | 330 mm | Q1 |
| UM13082FEESA | SOP8 | 12 mm | 4 mm | 8 mm | 330 mm | Q1 |
| UM130821FEESE | SOP14 | 16 mm | 4 mm | 8 mm | 330 mm | Q1 |

GREEN COMPLIANCE

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